HORIZON 2020

BADGER

Robot for Autonomous Underground Trenchless Operations, Mapping and Navigation

The goal of the project is the development of underground robotic system capable of:

- Trenchless drilling of subterranean curved small-diameter tunnels and capability for pipe installation
- Autonomous localization, mapping and navigation during its operation
- Intelligent location during operation to improve its perception and cognition abilities
- Less space for machine and machine equipment
- Increased maneuverability
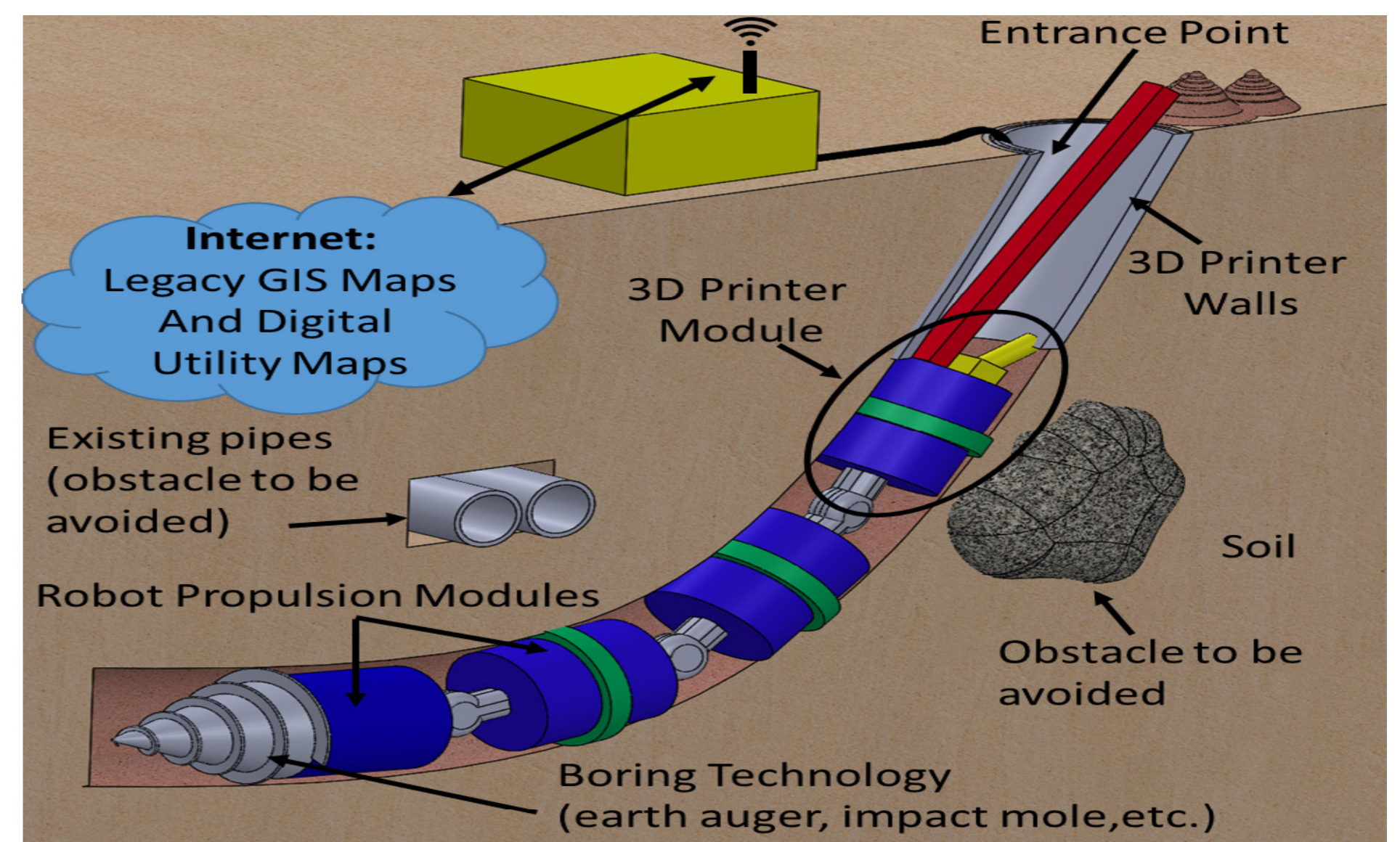
The expected strategic impact of the BADGER project focuses on:

- Introducing advanced robotic technologies, including intelligent control and cognition capabilities, to significantly increase European competitiveness.
- Drastically reducing the traffic congestion and pollution in the European urban environments increasing, in this way, the quality of life of citizens.
- Enabling technologies for new potential applications such as search and rescue, mining and quarrying, civil applications, mapping, etc.

Project Coordinator:

Prof. Carlos Balaguer,

University Carlos III of Madrid

RoboticsLab

Leganes (Madrid) Spain

balaguer@ing.uc3m.es

uc3m | Universidad Carlos III de Madrid

IDS GeoRadar

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